Grouped fuzzy SVM with EM-based partition of sample space for clustered microcalcification detection

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Abstract.

BACKGROUND: Detection of clustered microcalcification (MC) from mammograms plays essential roles in computer-aided diagnosis for early stage breast cancer.

OBJECTIVE: To tackle problems associated with the diversity of data structures of MC lesions and the variability of normal breast tissues, multi-pattern sample space learning is required.

METHODS: In this paper, a novel grouped fuzzy Support Vector Machine (SVM) algorithm with sample space partition based on Expectation-Maximization (EM) (called G-FSVM) is proposed for clustered MC detection. The diversified pattern of training data is partitioned into several groups based on EM algorithm. Then a series of fuzzy SVM are integrated for classification with each group of samples from the MC lesions and normal breast tissues.

RESULTS: From DDSM database, a total of 1,064 suspicious regions are selected from 239 mammography, and the measurement of Accuracy, True Positive Rate (TPR), False Positive Rate (FPR) and EVL = TPR* $\sqrt{1 - \text{FPR}}$ are 0.82, 0.78, 0.14 and 0.72, respectively.

CONCLUSION: The proposed method incorporates the merits of fuzzy SVM and multi-pattern sample space learning, decomposing the MC detection problem into serial simple two-class classification. Experimental results from synthetic data and DDSM database demonstrate that our integrated classification framework reduces the false positive rate significantly while maintaining the true positive rate.

Keywords: Pattern classification, EM algorithm, partition of sample space, grouped fuzzy SVM, computer aided detection

1. Introduction

Breast cancer is one of the most common causes of death among middle-aged women, with incidence increasingly on the rise during recent years. Mammography is the most widely used diagnostic technique for the early detection of breast cancer [1] because it is a low-cost, low-radiation-dose procedure with sufficient sensitivity to detect early-stage breast cancer. The most frequent markers of breast cancer are clustered MC [2], which appears in 30–50% of mammographic-diagnosed cases and shows a high correlation with breast cancer [3]. Therefore, the detection of MC in mammography is the most effective way of defeating breast cancer [4].

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S326 H. Wang et al. / Grouped fuzzy SVM with EM-based partition of sample space for clustered MC detection

Over the past dozen years, researchers have developed classifiers for better detection of MC, such as Artificial Neural Networks (ANN) [5,6] and Support Vector Machines (SVM) [7–9]. Dehghan showed that SVM with polynomial kernel and SVM with Gaussian RBF kernel achieve a higher true positive detection rate than Neural Networks (NN) [5]. Having evaluated the SVM, Kernel Fisher Discriminant (KFD), Relevance Vector Machine (RVM), Feedforward Neural Network (FNN), and Committee Machines, Wei concluded that the kernel-based method (SVM, KFD, and RVM) yielded the best performance [9]. However, because of the diversity features of the MC regions and the variability of normal breast tissues, single kernel SVM is still unable to provide a satisfactory accuracy rate.

To characterize this feature, researchers proposed to incorporate feature subspace learning algorithms into the classifiers. Li designed a combinational SVM [10] with the polynomial SVM to MC and the linear SVM to non-MC pixels, respectively, which achieved a significant reduction in false positive detection while simultaneously preserving the true positive detection rate. Zhang proposed an SVM-based approach by embedding General Tensor Discriminant Analysis (GTDA) of feature subspace learning [11]. Chang presented a Multiple Kernel Support Vector Machine with Grouped Features [12] to discern the inhomogeneous features in both MC lesions and normal breast tissues of suspicious regions, which reduced the false positive rate significantly and maintained the true positive rate. Zhang showed that the approach based on hybrid subspace fusion for MC detection [13] could obtain satisfactory sensitivity results as well as reduce the false positive rate.

In addition, two difficulties and challenges still exist when SVM is applied to the clustered MC detection problem. The first challenge is the complicated structural information of sample space, both in MC lesions and normal breast tissues space. Like many real-world problems, large amounts of samples imply that different classes may have different underlying data structures that exhibit different data distribution [14]. It has been shown that the structural information of data may contain useful prior domain knowledge for training a classifier [15]. Therefore, an ideal classifier should consider the structural information of the corresponding class and have a good discrimination ability of the within class diversities [16]. However, the traditional SVM-based classifiers mainly characterize the difference between different classes, which do not sufficiently consider the diversity within the classes [17]. Due to the fact that both MC lesions (positive class) and normal breast tissues (negative class) are inhomogeneous, we propose that single Probability Density Functions (PDF) based classification cannot fully characterize the diversified sub-patterns within classes, which requires multi-pattern sample space learning to both MC lesions and normal breast tissues space.

The second main challenge is the inability of the state-of-the-art methods to characterize different contributions of different samples for the classification. Oftentimes, some training samples are more important than others in a given classification task, i.e., the effects of the training points are different [18]. However, in traditional SVM, each training sample is treated as equally weighted, which makes the classifier very sensitive to outliers or noises in the training periods [19].

To address the above problems, a novel grouped fuzzy SVM algorithm with an EM-based partition of sample space called G-FSVM is proposed in this paper. To obtain the diversity of data structures and extract the structural information embedded within classes, the sample space of both MC lesions and normal breast tissues are considered as Gaussian Mixture Model (GMM), and each component of GMM represents a cluster of one objective class. GMM was chosen as the mixture model for the following reasons [20]: (1) It is reasonable from the center limit theorem. (2) It is convenient in calculation with Expectation-Maximization (EM) algorithm. (3) Any mixture model can be approximated to GMM theoretically by increasing the number of the model. Then, we estimate the parameter of GMM with EM algorithm and partition the sample space into several sub spaces. Specifically, the partition of sample

space based on EM preserves the diversity structural information of the sample space, which provides as much information as possible for the classifier of sub space. Each subset of samples of MC lesions and normal breast tissues are combined to train a suitable sub classifier. Furthermore, to address the second problem, we quantify the contribution of different samples and employ fuzzy SVM as the sub classifier of the final integrated classification. The fuzzy membership is defined by the probability of the samples belonging to the subset of sample space by EM estimation, which can denote the importance of the sample to the sub classifier. Taking these two factors into consideration, G-FSVM is presented to successfully characterize the diversified sub-patterns and the different importance of each sample, which cast the difficult two-class problem into a set of simple two-class classification problems.

The proposed G-FSVM differs in two ways from our previous method named Clustered Group Support Vector Machine (GC-SVM) [21]. One of the differences lies in the sample subspace learning algorithm. The partition of sample space in GC-SVM is completed with K-means clustering, which is strictly limited to distance computation, whereas the partition of sample space in G-FSVM is completed with EM algorithm for GMM based on probability computation [22]. Therefore, sample space characterization is based on statistics instead of geometrics, which is more stable in the diversity data structures. Another difference between these two methods is the choice of sub classifiers. In GC-SVM, traditional SVM is employed as the sub classifiers; however, in G-FSVM, the sub classifiers are fuzzy SVM, which takes full use of the different importance of each sample and has better discriminatory power.

Experimental results in both synthetic data and real clustered MC detection show that G-FSVM can significantly reduce the false positive rate while simultaneously maintaining the true positive rate for clustered MC detection as compared with the different kernel SVMs and our previous method GC-SVM.

The rest of the paper is organized as follows. Section 2 presents the EM-based partition of sample space and the integrated classification framework with fuzzy SVM. Section 3 describes the experimental results of both synthetic data and clustered MC detection. Finally, the paper is concluded in Section 4.

2. Methods

In this section, G-FSVM method for clustered MC detection from mammography is presented to deal with the diversity of underlying data structures in both MC lesions (positive class) and normal breast tissues (negative classes). Firstly, the sample spaces are modeled as GMM, and each Gaussian component represents a subspace of the MC lesions or the normal breast tissues. Secondly, EM algorithm is employed to estimate the parameters and the contributions of each Gaussian distribution. In this way, the training samples are divided into different groups, every sample in the specified group is attached the same label, and fuzzy membership values are simultaneously defined based on the probability of the samples belonging to the group. Finally, a series of fuzzy SVM sub-classifiers are integrated for MC detection.

2.1. EM-based sample space partition

Suppose the training set has M samples, i.e., $X = (x_1, \ldots, x_j, \ldots, x_M)$, for each sample x_j consisting of d features. Both the samples of MC lesions and normal breast tissues are considered as GMM, the distribution of the samples is modeled by a linear combination of two or more Gaussian distributions [20]. Assuming the training samples with d features are generated from Gaussian mixture model with N component, then:

E-Step: Given the current value of $\Theta^{(t)}$, the conditional distribution of Z = i is computed and substituted into the expectation of the log-likelihood function $Q(\Theta | \Theta^{(t)})$, which yields: $Q(\Theta | \Theta^{(t)}) = E_{Z|x,\Theta^{(t)}} [l(\Theta; x, Z = i)]$ M-Step: The optimal parameters $\Theta^{(t+1)}$ are chosen for the current weights by maximizing the expectation of $Q(\Theta | \Theta^{(t)})$, which yields: $\Theta^{(t+1)} = \arg \max_{\Theta} Q(\Theta | \Theta^{(t)})$

Fig. 1. Framework of EM algorithm.

$$p(\boldsymbol{x}|\Theta) = \sum_{i=1}^{N} a_i p_i(\boldsymbol{x}|\boldsymbol{\theta_i})$$
(1)

where $\Theta = (a_1, \ldots, a_N, \theta_1, \ldots, \theta_N)$, $a = (a_1, a_2, \ldots, a_N)$ is the weight of each distribution subjected to $\sum_{i=1}^N a_i = 1$, and p_i is the PDF of the *i*th Gauss component corresponding to parameter θ_i , which is mainly determined by mean vector μ_i and variance matrix Σ_i . Supposed the *j*th sample $x_j (j = 1, \cdots, M)$ generated by the Gaussian component with the corresponding parameter $\theta_i (i = 1, \cdots, N)$, that is

$$p_i(\boldsymbol{x}_j | \boldsymbol{\theta}_i) = \frac{1}{(2\pi)^{d/2} |\boldsymbol{\Sigma}_i|^{1/2}} \exp\left(-\frac{(\boldsymbol{x}_j - \boldsymbol{\mu}_i)^T (x_j - \boldsymbol{\mu}_i)}{2\boldsymbol{\Sigma}_i}\right)$$
(2)

For GMMs, the goal is to maximize the following log-likelihood:

$$l(\boldsymbol{\theta}) = \log p(\boldsymbol{x}|\Theta) = \sum_{j=1}^{M} \log \sum_{i=1}^{N} a_i p_i(\boldsymbol{x}_j|\boldsymbol{\theta}_i)$$
(3)

Unfortunately, maximizing the log likelihood Eq. (3) directly is often difficult because the log of the sum can potentially couple all of the parameters of the model [23]. However, if the estimation problem is reformulated in terms of so called latent or hidden variables $Z = i(i = 1, \dots, N)$ as

$$l(\Theta; x, Z = i) = \log p(\boldsymbol{x}|\Theta) = \sum_{j=1}^{M} \log \sum_{i=1}^{N} a_i p_i(\boldsymbol{x}_j | Z = i, \boldsymbol{\theta})$$
(4)

the log of the sum can be simplified and the maximization problem can be solved by many optimization algorithms [24]. As the latent variables cannot be observed directly, EM algorithm iteratively refines the maximum likelihood estimation by first calculating the expectation of the posterior of the latent variables Z, while keeping the parameters fixed. EM is a two-step algorithm with an expectation step and a maximization step represented in Fig. 1.

Under fairly mild regularity conditions, EM can be shown to converge to a local maximum of the likelihood. Although these conditions do not always hold in practice, EM iteration has been widely used

for maximum likelihood estimation for mixture models with good results [25]. It should be noted that the initial mean vector are randomly selected, the initial variance matrix is taken as whole data covariance matrix and the initial weights are set equally. The expectation and maximization steps are repeated until the convergence of Θ is reached.

With the estimated parameter Θ , the probability of every sample belonging to each Gaussian component distribution can be computed. The group label of the sample is assigned according to the maximum probability, and a kind of partition to the training sample space for the MC lesions and normal breast tissues are obtained, that is, the training data of the MC lesions and normal breast tissues data are divided into some different groups respectively. In addition, the weight of each distribution $a_i (i = 1, \dots, N)$ is regarded as the percentage of the corresponding group.

The component number N of the Gaussians should be determined before the iterative process of EM, however, for the fixed N, EM algorithm could estimate the parameter $\Theta = (a_1, \ldots, a_N, \theta_1, \ldots, \theta_N)$ for GMM as well as provide the log-likelihood function $l(\theta)$. Based on the relationship between the maximum likelihood function and entropy as determined by Akaike in 1977, the best solution for determining the number N is to minimize the Akaike Information Criterion (AIC) [26], which is defined as:

$$AIC = 2s - 2l(\boldsymbol{\theta}) \tag{5}$$

where s is the number of free parameters in the statistical model, and $l(\theta)$ is the log-likelihood for the model.

2.2. Grouped fuzzy SVM with partition of sample space

To clearly demonstrate our method G-FSVM, we present training process and testing process respectively.

In the training process, a model trained with integrated fuzzy SVM is proposed. Before formally describing the frame of the fuzzy SVM with partition of sample space, we first present and illustrate the idea of sample space partition in Fig. 2. Suppose that the samples of MC lesions (positive) and normal breast tissues (negative) are partitioned to m and k subsets, severally, and then each subsets of positive samples is combined with the negative samples. The clustered MC detection problem is casted into a total of $m \times k$ simple two-class classification problems.

Let D denote the training data set with n samples and d features for the clustered MC detection problem, that is:

$$D = \left\{ \left(\boldsymbol{x}_{i}, y_{i} \right) \middle| \boldsymbol{x}_{i} \in \boldsymbol{R}^{d}, y_{i} \in \{1, -1\} \right\}, i = 1, \cdots, n$$

$$(6)$$

where y_i is the corresponding desired output.

Based on the partition of sample space with EM, the subsets are given with its mean vector and variance matrix as:

$$D_{i}^{+} = \bigcup_{l=1}^{a_{i}^{+}n^{+}} (\boldsymbol{x}_{l}, P_{i}, s_{l}), \quad i = 1, \cdots, m$$
$$D_{j}^{-} = \bigcup_{l=1}^{a_{j}^{-}n^{-}} (\boldsymbol{x}_{l}, N_{j}, s_{l}), \quad j = 1, \cdots, k$$

where n^+ is the number of positive training samples, n^- the number of negative training samples, a_i^+ is the weight of the *i*th positive group, a_i^- is the weight of the *j*th negative group, P_i is the *i*th positive



Fig. 2. Partition of training sample space.

Fig. 3. Distance influenced by the dispersion of the sample sets.

group label, N_j is the *j*th negative group label, and s_l is the probability of sample x_l belong to D_i^+ or belong to D_i^- . Thus, the training data set can be described in another way:

$$D = D^+ \cup D^- = \left(\bigcup_{i=1}^m D_i^+\right) \bigcup \left(\bigcup_{j=1}^k D_j^-\right)$$

$$\tag{7}$$

By combining the samples with the subsets of D_i^+ and D_i^- , the training samples for the sub-classifiers are given as the following:

$$\begin{cases} T = \{ (\boldsymbol{x}_1, y_1, s_1), (\boldsymbol{x}_2, y_2, s_2), \cdots, (\boldsymbol{x}_L, y_L, s_L) \} \\ x_l \in \boldsymbol{R}^d, y_l \in \{P_i, N_j\}, 0 < s_l \leqslant 1 \\ i = 1, \cdots m, j = 1, \cdots k, l = 1, \cdots L \end{cases}$$
(8)

where $L = a_i^+ \cdot n^+ + a_j^- \cdot n^-$. The sub classifier F_{ij} $(i = 1, \dots, m, j = 1, \dots, k)$ can be trained with fuzzy SVM according to:

$$\begin{cases} \min \frac{1}{2} ||\boldsymbol{w}||^2 + C \sum_{l=1}^{L} s_l \xi_l \\ y_l(\boldsymbol{w}\boldsymbol{x}_l + b) \ge 1 - \xi_l \\ \xi_l \ge 0, l = 1, 2, \cdots, L \end{cases}$$

$$(9)$$

It is noted that after the partition of sample space, sub classifier F_{ij} may be imbalanced in size. In this paper, we adopt a simple synthetic minority over-sampling technique [27], where a few artificial samples are created based on the probability distribution of the existing minority samples from subset D_i^+ (or D_i^-) to balance the number between the majority and minority classes.

In the testing process, we need to predict the label of the under detection mammographic image sample **x**. The distance between **x** and each center of the subset D_i^+ $(i = 1, \dots, m)$ and $D_j^ (j = 1, \dots, k)$ is calculated. The appropriate sub classifier is selected according to the calculated distance, which is influenced by the tight density of the sample sets [28]. In Fig. 3, the distance between x and the center of data 1 is much farther than the distance between x and the center of data 2. Here, we prefer sample x to be much closer to data 1 because of the dispersion of data 1. To handle this condition, the Mahalanobis distance is used here.

Step 1:
Calculate the Mahalanobis distance between x and each
center of the subset D_i , and select D_{\min} and D_{secmin} ;
Step 2:
Predict the class label of unknown datum x directly or
with fuzzy SVM according to whether D_{\min} and D_{secmin} belong
to the same label class.

Fig. 4. Prediction algorithm.

The calculated Mahalanobis distance between x and each center of the D_i subset is indicated as $\gamma(x, D_i)$, and D_{\min} and $D_{sec\min}$ are defined as the following:

$$D_{\min} = \left\{ D^* \left| D^* \in D \boxplus \gamma \left(\boldsymbol{x}, D^* \right) = \min_{\substack{1 \leq i \leq m \\ 1 \leq j \leq k}} \left(\gamma \left(\boldsymbol{x}, D_i^+ \right), \gamma \left(\boldsymbol{x}, D_j^- \right) \right) \right\} \right\}$$
(10)

$$D_{\text{sec min}} = \left\{ D^* \left| D^* \in D - D_{\min} \mathbb{H}\gamma\left(\boldsymbol{x}, D^*\right) = \min_{\substack{1 \leq i \leq m \\ 1 \leq j \leq k}} \left(\gamma\left(\boldsymbol{x}, D_i^+\right), \gamma\left(\boldsymbol{x}, D_j^-\right)\right) \right) \right\}$$
(11)

When D_{\min} and $D_{\text{sec}\min}$ both belong to D^+ , the sample x is predicted as the MC lesions sample. In contrast, when D_{\min} and $D_{\text{sec}\min}$ both belong to D^- , the sample x is predicted as the normal breast tissues sample. Finally, when $D_{\min} \in D^+$ and $D_{\text{sec}\min} \in D^-$ or vice versa, the sample x is predicted according to the sub classifier with the combined sample sets of D_{\min} and $D_{\text{sec}\min}$. In summary, the prediction algorithm in Fig. 4 is performed to determine the class label of sample x.

3. Results

In this section, we compare our proposed G-FSVM with our previous method GC-SVM and traditional SVM with different kernels on both synthetic data sets and real clustered MC detection.

3.1. Synthetic data classification

To objectively estimate the performance of the proposed G-FSVM, we first test it in synthetic datasets. In our experiment, the first synthetic dataset consists of 400 random samples (vectors), and half of them are positive, with the rest being negative. Both the positive and negative samples are divided into two groups. They are all subject to Gaussian distribution. The positive class has its vectors distributed around the centers (-2, 0.5) and (2, -0.5) with variance 0.8. The negative class has its vectors distributed around the centers (-4.5, -1) and (4.5, 2) with variance 8. Figure 5 shows the distribution of the training samples for the first dataset.

There are a total of 600 samples for the second synthetic dataset. Half of these samples are positive samples, and the rest are negative ones. They are divided into three groups, respectively. Each group of the samples is subject to Gaussian distribution. The centers for the positive samples are (0, 5), (-6, -6).

S332 H. Wang et al. / Grouped fuzzy SVM with EM-based partition of sample space for clustered MC detection

Performance of different methods on the first synthetic dataset					
Methods	Acc	TPR	FPR	EVL	
Linear SVM	0.86	0.90	0.18	0.82	
Polynomial SVM	0.87	0.95	0.20	0.85	
Gaussian SVM	0.89	0.97	0.20	0.88	
GC-SVM	0.91	0.97	0.15	0.89	
G-FSVM	0.93	1	0.15	0.92	

 Table 1

 Performance of different methods on the first synthetic dataset

Table 1 lists the Accuracy, TPR, FPR and EVL of each kernel form of SVM, GC-SVM and G-FSVM.



Fig. 5. Distribution of the first synthetic dataset.

Fig. 6. Distribution of the second synthetic dataset.

-4) and (6, -4), and the centers for the negative samples are (0, 7.5), (-4.5, 0.5) and (4.5, -0.5). The variances for the positive and negative class are 1 and 5, individually. Figure 6 shows the distribution of the training samples for the second dataset. The testing set has the same number and distribution as the training set.

In this paper, $EVL = TPR^* \sqrt{1 - FPR}$ is used to evaluate the performances of the different methods. TPR is the ratio that the positive sample is correctly classified, and FPR is the ratio that the positive sample is wrongly classified. This measurement places more emphasize on TPR than FPR, which is reasonable in clustered MC detection; thus, the larger the EVL value is, the better the detection performance. The performance of G-FSVM is compared to the three different kernel forms of SVM [29]: the linear support vector machine (Linear SVM), polynomial support vector machine (Polynomial SVM), and Gaussian support vector machine (Gaussian SVM). Furthermore, the performance of the proposed method is also compared with GC-SVM, as presented in [21]. Tables 1 and 2 list the Accuracy, TPR, FPR and EVL of each kernel form of SVM, GC-SVM and G-FSVM.

Tables 1 and 2 show that: (1) The accuracy of the G-FSVM is better than those of the SVM with different kernels and GC-SVM, up to 2–4 percent. (2) The TPR of the G-FSVM is comparable with or better than those of other methods. (3) The GC-SVM and G-FSVM have a lower FPR than the different kernel SVMs. At 1 TPR, G-FSVM has a 0.15 and 0.22 FRP, which is about 5 percent less than those of SVM with different kernels. (4) G-FSVM has a higher EVL than the others, up to 3 percent more than GC-SVM. From these, it can be concluded that our proposed G-FSVM outperforms the different traditional SVMs and GC-SVM for the EVL measurement.

Performance of different methods on the second synthetic dataset					
Methods	Acc	TPR	FPR	EVL	
Linear SVM	0.85	0.96	0.27	0.82	
Polynomial SVM	0.85	0.98	0.28	0.83	
Gaussian SVM	0.87	1	0.27	0.85	
GC-SVM	0.87	0.98	0.23	0.86	
G-FSVM	0.89	1	0.22	0.89	

 Table 2

 Performance of different methods on the second synthetic dataset

Table 2 lists the Accuracy, TPR, FPR and EVL of each kernel form of SVM, GC-SVM and G-FSVM.

Table 3 Feature values used in G-FSVM				
Feature species	Feature (dimension)			
Gray feature	 Contrast Mean gray Variance Third (four)-order Average gradient Moment invariants 			
Geometry feature	 Circularity Degree of contraction Spherical Fourier descriptors 			
Texture feature	 Mean energy diagram Contrast Variance of the energy map Entropy Energy 			

Table 3 lists 63 typical low-level features which were calculated for each region, such as gray values, geometry and texture features, and so on.

Furthermore, the proposed method is less sensitive to the parameter selection than the SVM with different kernels. The results of the G-FSVM and GC-SVM presented above is computed by the linear kernels, and nearly the same performance can be calculated by the Gaussian and polynomial kernel.

3.2. Clustered microcalcification detection

The clustered MC detection data used in this paper comes from the DDSM dataset provided by the U.S. South Florida State University [30]. Suspicious regions of MC were detected by a segmentation algorithm that is described in [31]. The region sizes are variable, from 36*36 to 256*256, based on the detected size of the suspicious regions. Altogether 1,064 suspicious regions were selected from 239 mammography (with 496 positive samples and 568 negative samples). Examples of typical images are displayed in Fig. 7. Then, 63 typical low-level features were calculated for each region, such as gray values, geometry and texture features, and so on, which are grouped and listed in Table 3.

It should be noted that: (1) In EM algorithm, the initial covariance is taken as the sample covariance, and the initial means are estimated by fuzzy c-means method as usual. Additionally, the Gaussian component number of the MC lesions and normal breast tissues samples both are 3, calculated by Eq. (5). (2) The performance of the clustered MC detection data is the average results of five cross-validations.

Table 4 shows that: (1) G-FSVM has the highest accuracy (0.82). (2) The TPR of the G-FSVM is comparable to other methods. (3) The FPR of G-FSVM was nearly 10 percentage points less than GC-SVM,

\$334 H. Wang et al. / Grouped fuzzy SVM with EM-based partition of sample space for clustered MC detection

Performance of different methods on clustered MC detection						
Methods	Acc	TPR	FPR	EVL		
Linear SVM	0.74	0.78	0.29	0.64		
Polynomial SVM	0.75	0.79	0.29	0.67		
Gaussian SVM	0.75	0.78	0.27	0.67		
GC-SVM	0.77	0.78	0.23	0.68		
G-FSVM	0.82	0.78	0.14	0.72		

Table 4

Table 4 lists the performance comparisons of some different kernel forms of SVM, GC-SVM and G-FSVM on clustered MC detection.



Fig. 7. Breast tissue images.

which is much less than those of the different kernel SVMs. (4) As for the EVL measurement, G-FSVM has better performance than all of the other aforementioned methods. It performed up to 4 percent better than our previous method GC-SVM and even better than SVM with different kernels. From Table 4, it can be similarly concluded that our proposed G-FSVM performed superiorly on the clustered MC detection problem for the EVL measurement, which reduced the false positive rate significantly while simultaneously maintaining the true positive rate.

4. Conclusion

This paper presents a novel integrated classification framework to detect clustered MC called grouped Fuzzy SVM with EM-based partition of sample space (G-FSVM). The design of G-FSVM is aimed at the diversity of data structures of MC lesions and the variability of normal breast tissues. Specifically, the sample of the training space is considered to be generated from a GMM, with EM algorithm the training input sets of the MC lesions and normal breast tissues are partitioned into several groups, respectively. The partition of sample space based on EM maintains the structural diversity information of the sample space, which provides as much information as possible for the sub space classifier. After partition, each groups of the samples of MC lesions and normal breast tissues is combined to train a suitable sub classifier, and the MC detection problem is decomposed into serial simple two-class classification sub problems, which successfully characterizes the diversified sub-patterns of the sample space. Furthermore, to quantify the contribution of different samples, fuzzy SVM are employed as sub classifier of the final integrated classification. The fuzzy membership is defined by the probability of the samples belonging to the subset of sample space by EM estimation, which can denote the importance of the sample to the sub classifier. In this way, different samples with the proper levels of contribution are trained to the integrated fuzzy SVM to make the classification more effective. The experimental results

show that our integrated classification framework achieves a significant reduction in the false positive detection rate while also preserving the true positive detection rate as compared to the different kernel SVMs and the GC-SVM for the detection of clustered MC problem.

In future work, it would be interesting to integrate the grouped features to our proposed algorithm for clustered MC detection, which may obtain more useful prior knowledge both from inhomogeneous feature space and structural diversity sample space. We will also hope that G-FSVM can be applied to many real-world applications.

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Conflict of interest

None to report.

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S336 H. Wang et al. / Grouped fuzzy SVM with EM-based partition of sample space for clustered MC detection

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